

# CALL FOR PAPERS

## Journal of Robotics and Mechatronics

### Special Issue on “Tactile and Proximity Sensing” Vol.38 No.3 (June 2026), Fuji Technology Press, Japan

**Focus:** Technology for recognizing contact or proximity has been a key challenge in fields, such as robotic manipulation and human-robot interactions. Unlike in vision sensors, the structure and specifications of tactile and proximity sensors have not been standardized yet. Robots have various bodies depending on their purpose and environment they operate in, and physical contact in the context of robots is closely related to the means of achieving their objectives. Therefore, sensors related to state estimation naturally exhibit diverse configurations. This special issue discusses various possibilities relevant to contact and pre-touch recognition technologies. We welcome papers proposing new principles, configurations, and output information for tactile and proximity sensors, as well as system integration, interaction control, and verification through real-world tasks for their applications.

**Guest Editors:** Yosuke SUZUKI, Assoc. Prof., Kanazawa University, Japan

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#### Important Dates:

**Submission deadline**

**November 20, 2025**

**(For submissions in Japanese**

**November 6, 2025)**

Notification of acceptance/rejection

March 20, 2026

Final manuscript submission

April 20, 2026

**Publication**

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#### **Submission to:**

*Fujipress Manuscript Manager:* <https://mm.fujipress.jp/jrm>

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Indexed in: *ESCI, Scopus, Compexend, and DOAJ*

**Contact:** JRM Editorial Office, Fuji Technology Press, Japan (robot@fujipress.jp)

- ◆ Papers should be submitted in Microsoft Word or PDF format. Details on submission and the journal are available at the following link: <https://www.fujipress.jp/jrm/>
- ◆ Submissions can be either Japanese or English. Submissions in Japanese will be translated by Fuji Technology Press Ltd., at the authors' expense, and undergo full peer review.
- ◆ Papers submitted to this special issue will undergo our usual review process. Paper may be published in general issues based on review results.

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