CALL FOR PAPERS Journal of Robotics and Mechatronics

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Focus: Research has been ongoing on various types of soft robots in recent years. Soft robots with flexible mechanisms are expected to contribute greatly to the development of robotics, not only in industrial applications but also in various other applications, such as tasks involving robot-human interactions. Flexible mechanisms are not necessarily realized with flexible materials alone; they can also be realized by taking new approaches to conventional mechanisms. It is also desirable for sensors and various other components to be flexible so that they do not reduce the flexibility of a mechanism. The development of these mechanisms and elemental technologies will lead to the further development of soft robots. This special issue will feature papers on the structures and applications of soft mechanisms and soft elements, as well as on design and analysis methods and control techniques. We welcome many submissions so that we may contribute to the further development of soft robots. JRM Web site

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 Papers should be submitted in Microsoft Word or PDF format. Details on submission and the journal are available at the following link: https://www.fujipress.jp/jrm/

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- Submissions can be either Japanese or English. Submissions in Japanese will be translated by the publisher and used after being proofread by the author.
- Papers submitted to this special issue will undergo our usual review process. Paper may be published in general issues based on review results.

