

Paper:

# On Cluster Extraction from Relational Data Using $L_1$ -Regularized Possibilistic Assignment Prototype Algorithm

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[Received April 20, 2014; accepted August 25, 2014]

This paper proposes entropy-based  $L_1$ -regularized possibilistic clustering and a method of sequential cluster extraction from relational data. *Sequential cluster extraction* means that the algorithm extracts cluster one by one. The assignment prototype algorithm is a typical clustering method for relational data. The membership degree of each object to each cluster is calculated directly from dissimilarities between objects. An entropy-based  $L_1$ -regularized possibilistic assignment prototype algorithm is proposed first to induce belongingness for a membership grade. An algorithm of sequential cluster extraction based on the proposed method is constructed and the effectiveness of the proposed methods is shown through numerical examples.

**Keywords:** assignment prototype algorithm, possibilistic clustering,  $L_1$ -regularization, sequential cluster extraction, relational data

## 1. Introduction

The aim of cluster analysis called *clustering*, is to discover important structures and features from massive complex databases. Clustering, a data analysis method, divides a set of objects into groups called clusters. Objects classified in the same cluster are considered similar, while those classified in a different cluster are considered dissimilar. Hard  $c$ -means [1] and fuzzy  $c$ -means clustering (FCM) are the most well known clustering methods [2–4], as is possibilistic clustering (PCM), known to be useful from the viewpoint of robustness against noise and outliers [5]. Robustness against noise and outliers is essential if clustering methods are to be useful in real-world applications. Several variations have been proposed and studied based on PCM [6, 7]. The noise clustering concept has been proposed to overcome the negative effect of noise and outliers [8–10]. A method of sequential cluster extraction has even been proposed using this drawback [8]. Significant algorithms that extract “one cluster

at a time” have also been proposed [7, 11]. The sequential cluster extraction algorithm need not determine the number of clusters in advance – an advantage important when handling massive and complex data sets for detecting dense clusters.

Conventional clustering methods such as FCM and PCM generally handle numerical objects in the form of  $p$ -dimensional vector sets. Relational data, in contrast, are obtained from various social phenomena, e.g., social networks and e-commerce [12]. Relational data consist of measures of similarity or dissimilarity between objects. Many clustering methods have been proposed to handle such relational data [13–18]. The cluster center referred to as representative of a cluster is not used in these methods, and the membership degree of each object to each cluster is calculated directly from dissimilarities between objects. In the fuzzy non-metric model (FNM) of relational clustering methods, in which the membership degree of each object to each cluster is calculated directly from dissimilarities between objects [13, 16]. The assignment-prototype algorithm (AP) [18] and relational fuzzy  $c$ -means clustering (RFCM) [14] are also clustering methods used for relational data. FNM and AP handle both Euclidean and non-Euclidean relational data, whereas RFCM handles only Euclidean relational data. Non-Euclidean relational fuzzy  $c$ -means has been proposed to handle non-Euclidean relational data from that sense [15].

A probabilistic constraint on membership grade is used in FCM to denote that the sum of membership degrees is equal to 1. Noise and outliers cause negatively affect clustering results by FCM because of such a constraint. A possibilistic constraint is used instead of a probabilistic constraint in PCM [5], so a particular additional term for the membership degree is added in an objective function to obtain nontrivial solutions. In the machine learning field and related research, the  $L_1$ -regularization term is well known and useful for inducing sparseness [19, 20]. Sparseness means that a small variables are calculated as zero. In the clustering field, the sparse possibilistic clustering method has been proposed by introducing  $L_1$ -regularization [21] to obtain sparse results by calculat-



ing small degrees of membership as zero. This means that sparseness is induced from the viewpoint of not being in the cluster. Sparseness for being in the cluster is also considered in the clustering field. In that sense,  $L_1$ -regularized possibilistic clustering and its classification function have been proposed and described [22]. The sequential cluster extraction algorithm has also been constructed based on the  $L_1$ -regularized possibilistic clustering.

In this paper, we propose an entropy-based  $L_1$ -regularized assignment prototype algorithm (e $L_1$ PAP) to handle relational data. We construct the sequential cluster extraction algorithm to extract “one cluster at a time” from relational data. We also show the effectiveness of the proposed method through numerical examples.

This paper is organized as follows: In Section 2, we introduce symbols, fuzzy clustering and possibilistic clustering. In Section 3, we formulate an optimization problem and construct the e $L_1$ PAP algorithm. In Section 4, we construct the sequential cluster extraction algorithm based on e $L_1$ PAP. In Section 5, we review the results for the proposed method with datasets, and in Section 6, we present conclusions.

## 2. Preparation

The set of objects to be clustered is given and denoted by  $X = \{x_1, \dots, x_n\}$  in which  $x_k$  ( $k = 1, \dots, n$ ) is an object. In most cases,  $x_1, \dots, x_n$  are  $p$ -dimensional vectors  $\mathfrak{R}^p$ , that is, object  $x_k \in \mathfrak{R}^p$ . A cluster is denoted as  $C_i$  ( $i = 1, \dots, c$ ). The membership degree of  $x_k$  belonging to  $C_i$  is denoted as  $u_{ki}$  and a partition matrix is denoted as  $U = (u_{ki})_{1 \leq k \leq n, 1 \leq i \leq c}$ .

### 2.1. Assignment Prototype Algorithm

Several clustering methods for relational data have been proposed. One example is fuzzy non-metric model (FNM) of FCM-type clustering methods for relational data based on optimizing an objective function under the membership grade constraint [13, 16].

FNM depends strongly on initial values [16]. An assignment prototype algorithm (FAP) has been proposed as a clustering method for relational data to achieve robustness for initial values [18]. The objective function of FAP is similar to and yet a bit different from the objective function of FNM. Two variables, i.e., membership grade  $u_{ki}$  and prototype weight  $w_{ti}$ , are used in the assignment prototype algorithm. Windham considers the following objective function:

$$J_{fap}(U, W) = \sum_{i=1}^c \sum_{k=1}^n \sum_{t=1}^n (u_{ki})^2 (w_{ti})^2 r_{kt}$$

where  $W = (w_{ti})_{1 \leq t \leq n, 1 \leq i \leq c}$ , is the prototype weight and  $r_{kt}$  is the distance measure between objects. The proba-

bilistic constraint for  $u_{ki}$  is as follows:

$$\mathcal{U}_f = \left\{ (u_{ki}) : u_{ki} \in [0, 1], \sum_{i=1}^c u_{ki} = 1, \forall k \right\}. \quad (1)$$

The constraint for  $w_{ti}$  is as follows:

$$\mathcal{W}_f = \left\{ (w_{ti}) : w_{ti} \in [0, 1], \sum_{t=1}^n w_{ti} = 1, \forall i \right\}. \quad (2)$$

An entropy-based assignment prototype algorithm (eFAP) is considered in the same manner as in [3, 13]. The objective function of eFAP is as follows:

$$J_{efap}(U, W) = \sum_{i=1}^c \sum_{k=1}^n u_{ki} w_{ti} r_{kt} + \lambda_u \sum_{i=1}^c \sum_{k=1}^n u_{ki} \log u_{ki} + \lambda_w \sum_{i=1}^c \sum_{t=1}^n w_{ti} \log w_{ti}, \quad \dots \quad (3)$$

where  $\lambda_u > 0$  and  $\lambda_w > 0$  are fuzzification parameters. Constraints for  $u_{ki}$  and  $w_{ti}$  are the same as for Eqs. (1) and (2).

The formulation of FAP and eFAP is similar to that of fuzzy  $c$ -medoids [12] and related to the FCM-type co-clustering model [23].

### 2.2. Possibilistic Clustering

FCM is not robust against noise and outliers due to constraint  $\mathcal{U}_f$ . The main idea of possibilistic clustering (PCM) is to reduce the influence of noise and outliers on a data set [5, 9]. We introduce two objective functions of PCM:

$$J_{ps}(U, V) = \sum_{k=1}^n \sum_{i=1}^c (u_{ki})^m d_{ki} + \sum_{i=1}^c \eta_i \sum_{k=1}^n (1 - u_{ki})^m, \\ J_{pe}(U, V) = \sum_{k=1}^n \sum_{i=1}^c u_{ki} \{d_{ki} + \lambda u_{ki} (\log u_{ki} - 1)\},$$

where  $m > 1$ ,  $\eta_i > 0$  and  $\lambda_u > 0$  are parameters for PCM.

The constraint  $\mathcal{U}_f$  is not used in PCM, but additional terms for  $u_{ki}$  are added to derive a nontrivial solution. Condition  $\mathcal{U}_p$  is written as follows:

$$\mathcal{U}_p = \left\{ (u_{ki}) : u_{ki} \in [0, 1], \forall k \right\}, \quad \dots \quad (4)$$

where we have omitted original constraint  $0 < \sum_{k=1}^n u_{ki} \leq n$ .

The above objective functions are typical examples of PCM [4]. Sparse possibilistic clustering has also been proposed by introducing  $L_1$ -regularization [21]:

$$J_{sp}(U, V) = \sum_{k=1}^n \sum_{i=1}^c \{(u_{ki})^m d_{ki} + \gamma |u_{ki} - \alpha|\},$$

where  $m > 1$  and  $\gamma > 0$  are parameters. Parameter  $\alpha > 0$  is called a baseline constant [20]. This method induces sparseness for calculating the small membership grade as zero.

### 3. Proposed Method

#### 3.1. Entropy-Based $L_1$ -Regularized Possibilistic Assignment Prototype Algorithm

We propose a new possibilistic clustering method for relational data, called entropy-based  $L_1$ -regularized possibilistic assignment prototype algorithm (e $L_1$ PAP). We consider the following objective function for e $L_1$ PAP:

$$J_{elpap}(U, W) = \sum_{i=1}^c \sum_{k=1}^n \sum_{t=1}^n u_{ki} w_{ti} r_{kt} + \lambda_w \sum_{i=1}^c \sum_{t=1}^n w_{ti} \log w_{ti} \\ + \lambda_u \sum_{i=1}^c \sum_{k=1}^n u_{ki} (\log u_{ki} - 1) \\ + \gamma \sum_{i=1}^c \sum_{k=1}^n |1 - u_{ki}|.$$

$\lambda_w > 0$ ,  $\lambda_u > 0$ , and  $\gamma > 0$  are the parameters of e $L_1$ PNM. The condition for  $u_{ki}$  remains the same as for Eq. (4) and that for  $w_{ti}$  remains the same as for Eq. (2). In the following discussion of e $L_1$ PAP,  $d_{ki}$  and  $g_{ti}$  are as follows:

$$d_{ki} = \sum_{t=1}^n w_{ti} r_{kt}, \\ g_{ti} = \sum_{k=1}^n u_{ki} r_{kt}.$$

The optimal solution of  $w_{ti}$  is derived as follows:

$$w_{ti} = \frac{\exp(-\lambda_w^{-1} g_{ti})}{\sum_{q=1}^n \exp(-\lambda_w^{-1} g_{qi})}. \quad (5)$$

The main problem in constructing the algorithm of e $L_1$ PAP is how to derive the optimal solution of  $u_{ki}$ . Each membership  $u_{ki}$  could be solved separately in an e $L_1$ PAP procedure because of a condition  $\mathcal{U}_p$ . We thus first consider the following semi-objective function:

$$J_{elpap}^{ki}(u_{ki}) = u_{ki} d_{ki} + \lambda_u u_{ki} (\log u_{ki} - 1) + \gamma |1 - u_{ki}|.$$

We decompose  $1 - u_{ki} = \xi^+ - \xi^-$ , to obtain partial derivatives for  $u_{ki}$  in which all element of  $\xi^+$  and  $\xi^-$  are non-negative. The semi-objective function is rewritten by using a decomposition method [20] as follows:

$$J_{elpap}^{ki}(u_{ki}) = u_{ki} d_{ki} + \lambda_u u_{ki} (\log u_{ki} - 1) + \gamma (\xi^+ + \xi^-).$$

Constraints are as follows:

$$1 - u_{ki} \leq \xi^+, \quad 1 - u_{ki} \geq -\xi^-, \quad \xi^+, \xi^- \geq 0.$$

Introducing Lagrange multipliers  $\beta^+$ ,  $\beta^-$ ,  $\psi^+$ , and  $\psi^- \geq 0$ , Lagrangian  $L^{lp}$  is as follows:

$$L^{elpap} = u_{ki} d_{ki} + \lambda_u u_{ki} (\log u_{ki} - 1) + \gamma (\xi^+ + \xi^-) \\ + \beta^+ (1 - u_{ki} - \xi^+) + \beta^- (-1 + u_{ki} - \xi^-) \\ - \psi^+ \xi^+ - \psi^- \xi^-. \quad (6)$$

From  $\partial L^{elpap} / \partial \xi^+ = 0$  and  $\partial L^{elpap} / \partial \xi^- = 0$ ,

$$\gamma - \beta^+ - \psi^+ = 0, \quad \gamma - \beta^- - \psi^- = 0. \quad (7)$$

Since  $\psi^+$ ,  $\psi^- \geq 0$ , conditions  $0 \leq \beta^+ \leq \gamma$  and  $0 \leq \beta^- \leq \gamma$  are obtained from Eq. (7). Substituting Eq. (7) into Eq. (6), Lagrangian  $L^{elpap}$  is simplified as follows:

$$L^{elpap} = u_{ki} d_{ki} + \lambda_u u_{ki} (\log u_{ki} - 1) + \beta (1 - u_{ki}). \quad (8)$$

Here,  $\beta = \beta^+ - \beta^-$  and satisfies  $-\gamma \leq \beta \leq \gamma$ .

From  $\partial L^{elpap} / \partial u_{ki} = 0$

$$u_{ki} = \exp\left(-\frac{d_{ki} - \beta}{\lambda_u}\right). \quad (9)$$

Substituting the above for  $L^{elpap}$ , the Lagrangian dual problem is written as follows:

$$L_d^{elpap} = \beta - \lambda_u \exp\left(-\frac{d_{ki} - \beta}{\lambda_u}\right).$$

From  $\partial L_d^{elpap} / \partial \beta = 0$ , this dual problem is solved as

$$\beta = d_{ki}. \quad (10)$$

The optimal solution of the primary problem is derived by considering Eq. (9), Eq. (10) and  $-\gamma \leq \beta \leq \gamma$ .  $\beta < 0$  is not realized because  $d_{ki}$  is always positive. For  $0 \leq \beta \leq \gamma$ , the optimal solution is  $u_{ki} = 1$  because  $\beta = d_{ki}$ . For  $\gamma < \beta$ , the optimal solution is  $u_{ki} = \exp\left(-\frac{d_{ki} - \gamma}{\lambda_u}\right)$ . The optimal solution for  $u_{ki}$  of e $L_1$ PAP is derived as follows:

$$u_{ki} = \begin{cases} 1 & 0 \leq d_{ki} \leq \gamma \\ \exp\left(-\frac{d_{ki} - \gamma}{\lambda_u}\right) & \gamma < d_{ki} \end{cases} \quad (11)$$

#### 3.2. e $L_1$ PAP Algorithm

The e $L_1$ PAP algorithm is described as **Algorithm 1** based on the previous discussion:

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##### Algorithm 1 e $L_1$ PAP algorithm

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**e $L_1$ PAP 1** Set initial values and parameters.

**e $L_1$ PAP 2** Calculate  $u_{ki} \in U$  as follows:

$$u_{ki} = \begin{cases} 1 & 0 \leq d_{ki} \leq \gamma \\ \exp\left(-\frac{d_{ki} - \gamma}{\lambda_u}\right) & \gamma < d_{ki} \end{cases}$$

**e $L_1$ PAP 3** Calculate  $w_{ti} \in W$  as follows:

$$w_{ti} = \frac{\exp(-\lambda_w^{-1} g_{ti})}{\sum_{q=1}^n \exp(-\lambda_w^{-1} g_{qi})}.$$

**e $L_1$ PAP 4** If the convergence criterion is satisfied, stop. Otherwise go back to **e $L_1$ PAP 2**.

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## 4. Sequential Cluster Extraction Algorithm

The objective function of PCM is minimized separately because the probabilistic constraint used in FCM is not used in PCM [9]. This implies the drawback that a cluster centers obtained by PCM would have exactly the same results. The sequential cluster extraction algorithm is constructed by developing this drawback. The basis of this algorithm was previously proposed and discussed [7, 9, 10]. We construct the sequential cluster extraction algorithm by using the proposed method. The object has small  $d_{ki}$  classified in a compact cluster. The membership grade of such data can then be calculated as  $u_{ki} = 1$  by using Eq. (11). These data should be classified in the same cluster, which satisfies  $u_{ki} = 1$ . eL<sub>1</sub>PAP can thus extract one cluster at a time by minimizing the objective function in  $c = 1$ . The sequential cluster extraction algorithm by eL<sub>1</sub>PAP is described as **Algorithm 2**.

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**Algorithm 2** Sequential cluster extraction algorithm based on proposed methods

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**STEP 1** Give  $X$ , initial values  $u_{ki}$ ,  $w_{ti}$ , and parameters  $\lambda_u$ ,  $\lambda_w$ , and  $\gamma$ .

**STEP 2** Repeat the eL<sub>1</sub>PAP algorithm with  $c = 1$  until the convergence criterion is satisfied.

**STEP 3** Extract  $\{x_k \mid u_{ki} = 1\}$  from  $X$ .

**STEP 4** If  $X = \emptyset$  or the maximum number of repetitions is satisfied, stop. Otherwise give initial values and go back to **STEP 2**.

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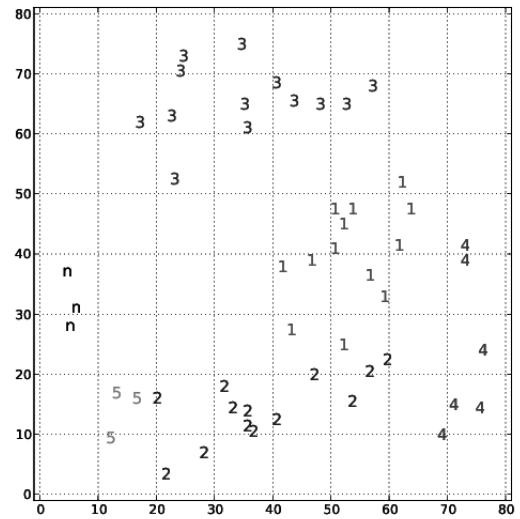
Parameter  $\gamma$  plays an important role in extracting clusters one by one. Previous studies mentioned a procedure for determining the sequential cluster extraction parameter [8, 10]. Based on that research, we construct the updating procedure for  $\gamma$  as follows:

$$\gamma = \rho \left[ \frac{\sum_{k=1}^{|X|} \sum_{i=1}^c d_{ki}}{|X|} \right] \dots \dots \dots (12)$$

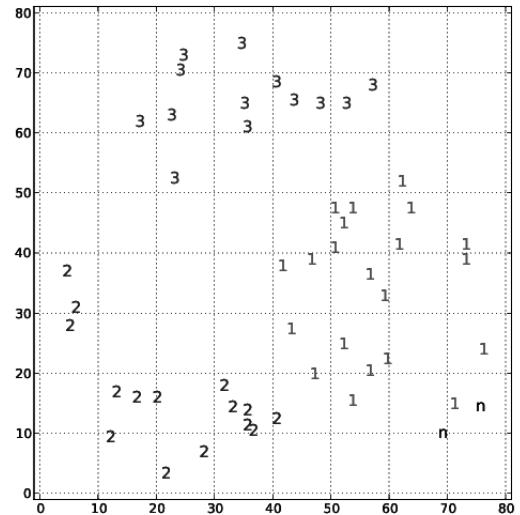
$\rho > 0$  is a scale multiplier that must be determined in advance.  $|X|$  means the number of objects handled in STEP 2. Parameter  $\gamma$  is updated in **Algorithm 2** by using Eq. (12).

## 5. Numerical Examples

We show the numerical examples of sequential cluster extraction using the Polaris and Iris datasets. The parameters which are used in eL<sub>1</sub>PAP are fixed  $\lambda_u = 1.0$  and  $\lambda_w = 100.0$ . The squared Euclidean norm is used as the distance measure between  $x_k$  and  $x_t$ , i.e.,  $r_{kt} = \|x_k - x_t\|^2$ .



**Fig. 1.** Sequential cluster extraction by eL<sub>1</sub>PAP with  $\lambda_u = 1.0$ ,  $\lambda_w = 100.0$ , and  $\rho = 0.4$ . The number of extracted clusters is 5 and the number of noise objects is 3.



**Fig. 2.** Sequential cluster extraction by eL<sub>1</sub>PAP with  $\lambda_u = 1.0$ ,  $\lambda_w = 100.0$ , and  $\rho = 0.7$ . The number of extracted clusters is 3 and the number of noise objects is 2.

### 5.1. Polaris Dataset

We start with the results of the proposed method with the Polaris dataset, which consists of 51 objects with 2 attributes and should be classified into three clusters.

**Figures 1 and 2** are illustrative examples of sequential cluster extraction by eL<sub>1</sub>PAP. The value displayed at each data point denotes the sequence for extracting clusters. The letter ‘n’ denotes the noise objects. We show the effectiveness of the proposed method by evaluating the results of the average and standard derivation of the Rand index (RI) [24], the number of extracted clusters, and the number of noise objects as listed in **Table 1**. The proposed algorithm extracts some *good* clusters and does



**Table 1.** Results of 100 trials of sequential cluster extraction by  $eL_1$ PAP with the Polaris dataset.

$\rho$	Rand Index		Num. of clusters		Num. of noise	
	Ave	SD	Ave	SD	Ave	SD
0.1	0.703	0.009	9.71	0.516	11.18	2.075
0.2	0.770	0.009	8.57	0.863	1.55	1.445
0.3	0.779	0.016	7.16	0.946	1.04	1.174
0.4	0.804	0.022	5.59	0.722	1.90	1.005
0.5	0.863	0.028	5.18	0.712	1.89	0.646
0.6	0.887	0.030	5.31	0.956	1.58	0.961
0.7	0.923	0.053	3.95	0.792	1.86	0.510
0.8	0.866	0.036	5.64	0.625	0.19	0.560
0.9	0.759	0.018	5.87	0.336	0.00	0.000
1.0	0.693	0.014	5.02	0.346	0.00	0.000

not extract noise objects. Noise objects are the objects not extracted until the convergence criterion is satisfied and consists of a noise cluster. In **Table 1**, the number of clusters means the number of *good* clusters. The number of repetitions is set to 10 as the convergence criterion in this numerical experiment. In these tables, Ave and SD means average and standard variation.

**Figures 1 and 2** show that some rough clusters are extracted and some noise objects are not extracted by the proposed algorithm. It also shows that parameter  $\rho$  used in Eq. (12) affects the results of sequential cluster extraction. The case with  $\rho = 0.7$  takes better results and seems to be suitable for the Polaris dataset, the larger the  $\rho$ , the smaller the number of extracted clusters. The number of noise objects is from **Table 1**. Large  $\rho$  induces large  $\gamma$  that takes a broad area that satisfies  $u_{ki} = 1.0$ . These tables show that the proposed algorithm is robust for initial values because the value of SD is quite small. Parameter  $\gamma$  further influences the classification results and sequential cluster extraction.

## 5.2. Iris Dataset

Next, we show the results of proposed methods with the Iris dataset published in the UCI machine learning repository.<sup>1</sup> The Iris dataset consists of 150 objects with 4 attributes and should be classified into three clusters. We also show the results of proposed method with the average and standard deviation RI, the number of extracted clusters, and the number of noise objects in **Table 2**. In the case of  $\rho = 0.1$ , the algorithm does not extract a *good* cluster and all objects are classified into noise clusters. Many objects are also classified into noise clusters in the case of  $\rho = 0.2$  and  $\rho = 0.3$ . By evaluating the value of RI, the number of extracted clusters, and the number of noise objects comprehensively, parameter  $\rho$  is suitable for the Iris dataset between 0.4 and 0.8.

**Table 2.** Results of 100 trials of sequential cluster extraction by  $eL_1$ PAP with the Iris dataset.

$\rho$	Rand Index		Num. of clusters		Num. of noise	
	Ave	SD	Ave	SD	Ave	SD
0.1	0.329	0.000	0.00	0.000	150.00	0.000
0.2	0.518	0.006	1.00	0.000	113.62	1.420
0.3	0.806	0.024	2.24	0.472	37.37	5.416
0.4	0.795	0.003	3.01	0.099	13.23	1.535
0.5	0.790	0.003	3.49	0.806	4.20	2.631
0.6	0.782	0.001	3.96	0.196	3.17	0.788
0.7	0.780	0.001	3.42	0.494	2.62	0.690
0.8	0.779	0.000	3.37	0.730	3.07	1.645
0.9	0.778	0.000	5.00	0.000	0.00	0.000
1.0	0.777	0.000	5.00	0.000	0.00	0.000

## 6. Conclusions

We have proposed an entropy-based  $L_1$ -regularized possibilistic assignment prototype algorithm ( $eL_1$ PAP). We have also constructed a sequential cluster extraction algorithm based on  $eL_1$ PAP. The algorithm handles both  $p$ -dimensional objects  $x_k \in R^p$  and relational data ( $r_{kt}$ ). We have shown the effectiveness of the sequential cluster extraction algorithm through numerical examples.

In future work, we will compare the performance of the proposed sequential cluster extraction algorithm with other methods and benchmark datasets. We will also consider how to determine a better or more suitable parameter  $\rho$ , which plays an important role in the proposed method and algorithm.

## Acknowledgements

This study was supported in part by Telecommunications Advancement Foundation, JSPS KAKENHI Grant Numbers 26330270, and 26330271.

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