JOURNAL OF
Robotics and Mechatronics

Aims & Scope

The *Journal of Robotics and Mechatronics* (JRM) is a peer-reviewed journal in fields such as robotics, mechatronics, automation, system integration, and human-related technology. Its editorial board includes wellestablished researchers and engineers in the field from the world over.

The scope of the journal includes any and all topics on robotics and mechatronics. As a key technology in robotics and mechatronics, it includes actuator design, motion control, sensor design, sensor fusion, sensor networks, robot vision, audition, mechanism design, robot kinematics and dynamics, mobile robot, path planning, navigation, SLAM, robot hand, manipulator, nano/micro robot, humanoid, service and home robots, universal design, middleware, human-robot interaction, human interface, networked robotics, telerobotics, ubiquitous robot, learning, and intelligence.

The scope also includes applications of robotics and automation, and system integrations in the fields of manufacturing, construction, underwater, space, agriculture, sustainability, energy conservation, ecology, rescue, hazardous environments, safety and security, dependability, medical, and welfare, but not limited to them.

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