

Keyword Index of Journal of Robotics and Mechatronics Volume 36, 2024

- α -shapes algorithm..... 438
3D point cloud..... 63, 1001
- A**
accelerometer 229
accident 139
action probability 658
actuator..... 836
adaptive control..... 1098
admittance control..... 483
aerial image captured by drone... 721
aerial/aquatic robot..... 1122
affective expression..... 1481
agent..... 871
agricultural robot..... 1262
agriculture 1516
agriculture image processing 721
aircraft operations 1090
airspace integration 1090
altruistic behavior..... 546
anatomy trains..... 458
android robot..... 1481
angulation..... 1243
Antarctica..... 1179
arm assist..... 1191
arousal level 1481
articulated mobile robot
..... 1302, 1315, 1339
artificial muscle..... 251
attack angle of skis..... 1243
automated display shelf..... 1527
automatic construction 961
automatic dataset generation..... 721
automatic design 149, 538
automatic driving control..... 211
automatic findings generation..... 353
autonomous control..... 1072
autonomous driving .. 628, 642, 1516
autonomous driving technology.. 779
autonomous excavator 263
autonomous inspection..... 1302
- autonomous navigation 918
autonomous surface vehicle (ASV)
..... 449, 1507
autonomous system..... 1481
autonomous underwater vehicl
(AUV)..... 190, 449, 1507
auxetic structures 1428
axillary bud 201
- B**
backstepping strategy..... 1098
balloon..... 1167
Bayesian optimization..... 273, 758
biarticular muscle(s)..... 704, 711
BIM..... 343
bio-inspired robot
..... 251, 1143, 1448, 1468
bio-inspired structure 1010
bioengineering..... 690
biologically-inspired robots
..... 1315, 1328, 1357
biomechanics..... 406, 1235
body propagated vibration 1235
Bonabeau model..... 982
both water and air..... 1019
branch point 201
- C**
CACC..... 669
calibration 320
cardiovascular surgery training... 801
catheter..... 899
center of gravity 711
center of pressure 396
character..... 871
chemotaxis 982
cilia..... 1387
clap-and-fling..... 1122
collaborative learning..... 168
collaborative work system 961
communication..... 658, 871
communication protection 365
communication robot 158
configurable wing 1037
congested highway..... 779
connectivity maintenance..... 526
construction..... 334
construction automation..... 284
construction machine 211
construction work..... 320
construction work assistive robot
..... 1408
continuum robot with few actuators
..... 1369
control allocation 1255
control stability 21
control system 1043, 1055
convenience store..... 1527
convex programming 1082
cooperation..... 658
correlated uncertainty..... 1082
covariance control..... 1082
covariance steering..... 1082
coverage path planning 1262
crash avoidance..... 779
crawler robot 732
curling 864
curvature distribution 1369
cyber attack 669
cybernetic avatar 856
- D**
data fusion..... 79, 375
dead time compensation..... 211
decentralized system 546
decommissioning
..... 9, 63, 115, 139, 1537
decommissioning of nuclear power
plant 39
decommissioning robot..... 125
decontamination robot 95
deep learning..... 168, 343, 603

dementia..... 871
 depth image camera 694
 depth–depth matching algorithm 694
 determinant 139
 dextrous manipulation..... 758
 differential inclusion 483
 digital imaging and communication
 in medicine..... 694
 disconnection precursor detection
 365
 distributed Kalman filter 680
 docking–undocking drone..... 1026
 downtime reduction 365
 driver model 879
 driving robot..... 879
 driving-review robots..... 1577
 drone 1010, 1055
 dueling DQN (deep Q-network) . 589
 dynamic facial expression..... 1481
 dynamic floor field model..... 982
 dynamic graph..... 517
 dynamic manipulation..... 950
 dynamic reassignment..... 1262
 dynamic stability..... 1568

E

educational support robot..... 168
 elbow extension torque 1208
 electric vehicle 879
 electro-hydraulic servo system ... 889
 electromyogram 823
 electropermanent magnet 1026
 emergency response 134
 encoder 229
 energy and environment..... 690
 engage-disengage mechanism.... 406
 environmental modification 1438
 estimation of transformation 973
 evolutionary game..... 555
 excavation 334
 excavation robot..... 273
 exoskeleton 1191
 exploration 568
 extended Kalman filter..... 1378
 eye-tracking device 1055

F

face mask detection..... 1495
 fact check 555

filtering..... 669
 fixed-wing UAV 1179
 flapping wing 1134
 flapping-wing aerial vehicles
 1143, 1156
 flash memory 88
 flat slope..... 940
 flatworms 1468
 flexible grasping..... 1221
 flexible object manipulation 950
 flight control..... 1098
 flight control computer 1179
 flight efficiency 1010
 flight test 1167, 1179
 fluid power system..... 251
 force control 284
 force sensing 1156
 forceps..... 1550
 formation control system 449
 frequency response..... 899
 fuel debris..... 9, 71
 Fukushima Daiichi 9
 Fukushima Daiichi Nuclear Power
 Station 71, 107, 125
 Fukushima reconstruction 125
 funnel control 517

G

gait parameters 1568
 game..... 580
 gamma-ray irradiation..... 88
 genetic algorithm 628
 gliding 1134
 graph optimization 426
 grasping force..... 823
 gravity compensation 1191
 ground adaptability 732
 growing robot..... 415

H

Hall-effect sensor 229
 hand motion measurement 801
 hand-eye calibration..... 438
 hand-eye equation $AX=ZB$ 438
 heat absorption capacity..... 388
 helicoidal rolling motion..... 1378
 hexarotor drones..... 1255
 hierarchical control system 909
 hierarchical network..... 263

high altitude 1167
 high altitude decontamination..... 95
 high speed motion 1284
 high-speed camera 746
 human augmentation..... 309, 847
 human classification..... 1495
 human motor learning 973
 human symbiotic robots..... 1577
 human-robot interaction..... 158, 168
 hydraulic excavator..... 294, 309, 909
 hyper-redundant manipulator.... 1448
 hyper-redundant robots 1357

I

ICT construction 294
 identification 201
 image alignment..... 721
 image processing..... 1026
 image selection..... 1537
 imitation learning 263, 538
 implicit control..... 415
 in-context few-shot learning 353
 in-hand rotation..... 396
 indoor environment scanning..... 115
 inertial measurement unit..... 940
 inflatable robots 856
 information disorder..... 555
 information technology 690
 infrastructure inspection..... 746
 infrastructure maintenance..... 353
 interaction 732
 interactive task 1458
 interface..... 309
 intermittent flight 1134
 internal model 309, 823
 interpretability..... 658
 intertarsal joint 406
 inverse dynamics analysis..... 1208
 inverse kinematics..... 1273
 investigation 9
 irradiation..... 134

J

jamming transition phenomenon. 181
 Japanese honorifics 1577
 jerk limiter..... 483

K

k-means clustering 1262
 KANSEI..... 158
 KHG..... 134
 knee joint torque 711

L

landing guidance control.....1110
 landing motion 704
 landslide dam 415
 lane change..... 779
 large language model 353
 lateral branch..... 201
 launch window 1167
 LiDAR..... 294, 1516
 lighting facilities 746
 linear structured light 438
 link 181
 LMF 134
 local body shape control 1315
 localization..... 320, 375, 472
 locomotion 406
 locomotion on pipes..... 1396
 logistic regression 472
 long-reach manipulator 30
 low power wide area (LPWA)..... 589
 low-cost thermal chessboard..... 388
 lower limb exoskeleton robot..... 889
 lunar base 334

M

maintenance robots 1357
 manipulability 1568
 map utilization 642
 margin of stability 1208, 1568
 MCL..... 375
 mechanical compliance 732
 mechanical design 149, 1468
 mechanics and electronics..... 690
 mechanism design..... 1273
 mechatronics 690
 mild cognitive impairment..... 871
 minimum muscle-tension change
 1284
 mixed reality 694
 mixed-integer linear programming
 1090

mobile robot(s)
 415, 426, 472, 568, 928, 1495
 mobiligence..... 732
 mobility 334
 model error compensator (MEC)
 909
 model predictive control 1110
 model-based development (MBD)
 909
 modular robot..... 39, 1419
 modularized rail structure 39
 monotaxic (ditaxic) direct
 (retrograde) wave..... 1468
 moon landing 1110
 moth flame optimization 889
 motion control..... 1315, 1408
 motion design..... 1357
 motion on inclined planes 1438
 motion planning 758, 1396
 motion transmissibility..... 1273
 motor skill augmentation 847
 multi-agent 603
 multi-agent deep reinforcement
 learning 658
 multi-agent learning 580, 642
 multi-agent system
 508, 517, 589, 628, 1262
 multi-purpose module system
 (MMS) 1419
 multi-robot systems..... 526
 multi-trip time-dependent vehicle
 routing problem 1090
 multi-view stereo (MVS) 115
 multicopter 1019
 multiple AUVs 190
 multisensor network..... 680
 muscle property optimization 847
 muscular activity 704
 muscular force..... 1284
 musculoskeletal humanoid robot 458
 musculoskeletal robot 1284

N

naming..... 1577
 navigation..... 508
 negative Poisson's ratio..... 1428
 neural point process 603
 neutron sensor 71
 noise 1010

non-artificial objects environment
 1001
 non-pulley 1284
 noncooperation..... 618
 nonlinear programming..... 1110
 normal cone..... 483
 nuclear accident 125, 134
 nuclear power..... 107
 nuclear power plant
 decommissioning..... 49
 numerical optimization 263

O

object recognition..... 343
 obstacle avoidance .. 517, 1065, 1072
 ocean waves 229
 omnidirectional camera..... 1495
 onboard camera..... 1026
 open design approach..... 415
 optical flow 1537
 optimal control..... 1065
 ornithopter..... 1143
 outdoor flight experiments..... 1043
 overturn recovery 940

P

packet dropout..... 680
 parallel link 711
 parallel link mechanism .. 1037, 1550
 parallel mechanism 1273
 parameter design 823
 particle swarm optimization..... 889
 passive..... 1221
 passive mechanism..... 406
 path planning..... 30, 961
 pedal wave-driven locomotion.. 1468
 pedestrian avoidance..... 918
 performance 139
 persistent surveillance..... 526
 personal mobility vehicle..... 918
 photogrammetry..... 115, 1507
 physical therapy 813
 pick-and-place..... 181
 piezoresponse..... 899
 pipe..... 343
 pipe-inspection robot 1387
 planogram 1527
 pneumatic..... 836
 pneumatic actuator 864

- pneumatic artificial muscle 769
 pneumatic caisson method 961
 pneumatic pressure..... 1221
 point cloud 961
 polyvinylidene fluoride (PVDF)
 film..... 899
 population-based search..... 618
 positional control 1019
 positron emission tomography.. 1550
 postural stability..... 813
 potential energy..... 1243
 power assist..... 836
 power consumption minimization
 1255
 power-law..... 618
 product layout 1527
 product stocking robot 1527
 profit sharing..... 580
 propeller..... 1010
 prosthetic finger 1221
- Q**
 Q-learning 580
 quadrotor..... 1026, 1065, 1098
 quasi-passive dynamic walking .. 458
- R**
 radiation imaging 79
 radiation tolerance..... 88
 radioactive source 79
 radius of curvature 1243
 RANSAC 438
 Raspberry Pi..... 88
 reconfigurable robot..... 1328
 redundant robot 1419
 redundant system 1438
 regenerative brake control..... 879
 rehabilitation device..... 813
 reinforcement learning
 508, 538, 580, 589, 642
 remote center of motion mechanism
 1191
 remote construction..... 39
 remote control 95
 remote control technology 125
 retrofitted vehicle..... 211
 RGB-D camera..... 426
 road detection..... 1516
 robot 1055
- robot contest..... 95
 robotic manipulator 49
 robotics..... 9, 139, 508
 rope climbing 1348
 ROV 71
 rover 334
 RTK-GPS 472
- S**
 SBP..... 71
 scale-free 618
 seafloor survey 1507
 search and rescue activities..... 568
 search and rescue robots 1315
 self-position estimation..... 746
 self-powered..... 1221
 semantic localization..... 375
 semantic segmentation 63
 semi-autonomous stair-climbing
 1339
 sense of agency 856
 sense of body ownership..... 856
 sensor fusion 294
 sensorless force control..... 1458
 sequential pattern mining 603
 serial linkage mechanism..... 149
 series elastic actuator 284
 shape recovery 769
 shape-memory alloy..... 181, 769
 shape-memory polymer 769
 shoulder adduction torque..... 1208
 simple control..... 458
 situation awareness 526
 six-legged robot 940
 skiing technique 1243
 SLAM 79, 426, 1001
 slapping..... 1122
 smooth avoidance..... 918
 snake robot(s)..... 1302, 1339, 1348,
 1357, 1378, 1396,
 1419, 1438, 1458
 snake-like robot..... 1328, 1408
 snow field..... 928
 social and economic system..... 982
 social deception..... 555
 social insects 982
 social media dynamics 555
 social robot..... 158
 soft actuator..... 251
 soft robot 251, 836, 1428
- soft robotics..... 856, 1387, 1448
 spherical link mechanism..... 1273
 sports 603
 stability..... 1134
 standing up 711
 stem 201
 stochastic optimal control 1082
 strain gauge 1156
 structure and feature similarity
 of image 1558
 structure from motion (SfM)
 115, 1537
 support acceptability 1577
 surgical navigation 694
 surgical technique analysis..... 801
 survivability 546
 swarm intelligence 618
 swarm robotics 526, 538, 589
 synthetic fiber rope 21
- T**
 T-cane..... 1208
 tactile sensor..... 899
 tailsitter 1037
 takeoff 1122
 technique determination..... 801
 teleoperation..... 49
 tendon-drive 30
 tendon-driven 1369
 tennis volley 1235
 tension adaptation 1348
 throwing manipulation 758
 tile exterior walls..... 1043
 tiltrotor system 1019
 toilet floor..... 388, 1558
 toilet floor trash detection 1558
 toilet liquid waste..... 388
 toilet solid trash..... 1558
 total ionization dose 88
 trajectory generation 1065
 trajectory planning 49, 263
 trajectory update..... 1110
 travel efficiency..... 1328
 tunnel..... 746
 two-finger robot 396
 two-wheeled multi-copters..... 1043
- U**
 uncrewed aircraft systems..... 1090

underground pit..... 1302
 underwater robot 107, 1458
 underwater robotics..... 1387
 underwater survey 190
 undulatory locomotion 1428
 uneven-surface object 396
 unknown string..... 950
 unmanned aerial vehicles (UAV)
 1001, 1019, 1072, 1167
 unmanned construction 365
 unmanned operation..... 294
 unpaved road..... 1516
 user interface..... 39

V

vampire bat..... 546
 variable stiffness 181, 769
 vehicle 669
 vehicle dynamics..... 879
 vehicle-to-vehicle communication
 628, 642
 velocity control 864
 vibration suppression 483
 virtual agents..... 517
 virtual reality 823
 virtual wall 628
 visual feedback..... 309
 visual language model..... 353
 visual support..... 1055

W

wall hammering inspection systems
 1043
 water droplet detection..... 388
 water surface effect 1122
 wave height measurement..... 229
 wearable device..... 836
 weed area estimation..... 721
 well-being 158
 whale optimization algorithm 889
 wheel loader 211
 wheel odometry..... 426
 wheel robot..... 1419
 wheel-loader..... 273
 wheeled robot..... 928
 winding pipe..... 1302
 wire-driven mechanism..... 21
 wireless communication..... 365
 Wrong Fix 472