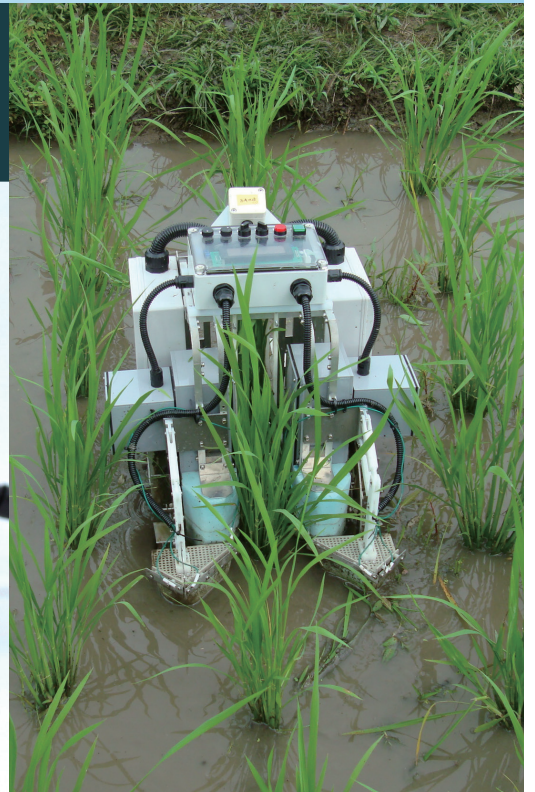
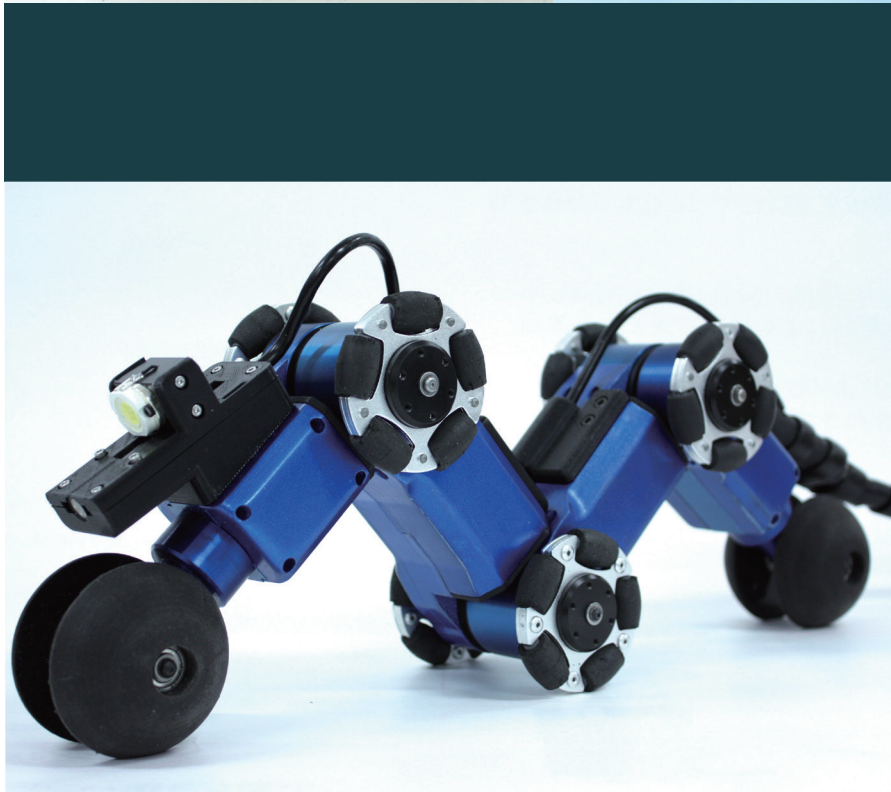


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Cover Pictures:

Upper left:  
Spherical and non-spherical combined 2DOF rotational parallel mechanism for microsurgical robotic system (Kyushu University)

Lower left:  
Mobile inspection robot “AIRo-2.2” (Ritsumeikan University)

Upper right:  
Drone “PF1-Survey” (Autonomous Control Systems Laboratory Ltd. (ACSL))

Lower right:  
Paddy weeding robot (IKOMA Robotech Corporation)

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