Journal of Robotics and Mechatronics 第36集 第2号 通營第210号 令和6年4月20日発行 ISSN 0915-3942

Journal of Robotics and Mechatronics

Vol.36 No.2 Apr. 2024

■ Special Issue on Advanced Robotic Technology and System for DX in Construction Industry

Journal of Robotics and Mechatronics is indexed in: ESCI; Scopus; Compendex (Ei)







Vol.36 No.2 Apr.





Cover Pictures:

Upper left:

Spherical and non-spherical combined 2DOF rotational parallel mechanism for microsurgical robotic system (Kyushu University)

Mobile inspection robot "AIRo-2.2" (Ritsumeikan University)

Upper right:

Drone "PF1-Survey" (Autonomous Control Systems Laboratory Ltd. (ACSL))

Paddy weeding robot (IKOMA Robotech Corporation)

This journal is indexed in:

Emerging Science Citation Index (ESCI); Scopus; Compendex (Ei); DBLP; UlrichswebTM Global Serials Directory; Genamics JournalSeek; Open J-Gate; J-Global; NDL Search; CiNii Articles; CNKI; CAB Abstracts; DOAJ

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Cover Design

Publisher

Published bimonthly by Fuji Technology Press Ltd.

Ichigo Otemachi North Bldg. 2F 1-15-7 Uchikanda, Chiyoda-ku, Tokyo 101-0047, Japan

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Printed copy: one year subscription Institutional rate JPY 138,000

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