

## To Contributors of Articles

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### Sample of personal data



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1987- Visiting Scientist, Massachusetts Institute of Technology

1989- NTT Human Interface Lab.

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- "Modeling the Special Dynamics of Robotic Manipulators with Flexible Links and Joint Clearances," ASME Journal of Mechanical Design, Vol.115, pp. 839-847, Dec., 1993.

**Academic Societies & Scientific Organizations:**

- The American Society of Mechanical Engineers (ASME)
- The Japan Society of Mechanical Engineers (JSME)
- The Robotics Society of Japan (RSJ)

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