

# *International Journal of Automation Technology*

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### **AIMS & SCOPE**

The *International Journal of Automation Technology* focuses on advanced automation technologies ranging from basic techniques to a variety of applications meeting industrial requirements. This covers automation technologies on design, manufacturing, assembly, inspection, transportation, logistics, machine tools, robotic system, and control systems and devices. While some journals focus solely on automation specific to scientific research, the *International Journal of Automation Technology* is the only journal that provides broad, comprehensive coverage, from engineering research and development papers to articles found in commercial magazines. This journal thus provides many practical examples relating advanced automation and reviews, research and development papers, news, and interviews, providing readers with much new, interesting, and informative topics directly applicable to their work.

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### <Journal article>

- [1] T. Arai et al., “Development of a direct-drive human-like manipulator,” J. Robotics Society of Japan, Vol.5, No.1, pp. 27-35, 1985.
- [2] H. Yang, T. Takaki, and I. Ishii, “Simultaneous dynamics-based visual inspection using modal parameter estimation,” J. Robot. Mechatron., Vol.23, No.1, pp. 180-195, 2011.

### <Journal article with DOI>

- [3] O. Schneider, K. MacLean, C. Swindells, and K. Booth, “Haptic experience design: What hapticians do and where they need help,” Int. J. of Human-Computer Studies, Vol.107, pp. 5-21, 2017. <https://doi.org/10.1016/j.ijhcs.2017.04.004>

### <Book chapter>

- [4] T. Mouri and H. Kawasaki, “A novel anthropomorphic robot hand and its master slave system,” M. Hackel (Eds.), “Humanoid Robots, Human-like Machines,” I-Tech Education and Publishing, pp. 29-42, 2007.

### <Book>

- [5] Rumelhart, McClelland and the PDP Research Group, “Parallel Distributed Processing,” The MIT Press, 1988.
- [6] M. Wisse and R. Q. v. d. Linde, “Delft pneumatic bipeds,” Springer-Verlag Berlin Heidelberg, 2007.

### <Conference paper>

- [7] J. Furusho et al., “A performance evaluation method of a passive-type force display and rehabilitation system with redundant brakes,” Proc. IEEE Int. Conf. on Rehabil. Robotics, pp. 950-955, doi: 10.1109/ICORR.2009.5209504, 2009.
- [8] T. Yamada and T. Morimatsu, “Remarks on RBF controller induced from neural network controller,” Proc. of the 34th SICE Annual Conf., pp. 725-726, 1996.

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- [9] “Three dimension motor,” Japanese Patent 1946377, 1985.
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A title and caption must be provided above each table. The caption should be brief, but informative, complete and clear.

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